

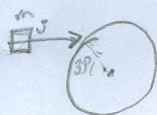
EUF 2011-2012

25/03/2016

18/00

Q1

a)



$$\tau = I \cdot \alpha$$

$$x_{cm} = \frac{\sum m_i x_i}{\sum m_i}$$

$$a_c = \frac{v^2}{R}$$

$$V_{cm} = \frac{\sum m_i v_i}{\sum m_i}$$

$$\Rightarrow (M+m) v_{cm} = m v$$

$$v_{cm} = \frac{m v}{M+m}$$

b)

$L_i = L_f$

$$m v R = I \omega \Rightarrow m v R = \omega \left(\frac{1}{2} M R^2 + m R^2 \right)$$

$$I = \frac{1}{2} M R^2 + m R^2$$

$$\omega = \frac{m v R}{\frac{1}{2} R^2 (M+m)} = \frac{2 v}{R} \left(\frac{1}{1 + \frac{M}{m}} \right)$$

$$c) E_i = \frac{m v^2}{2}$$

$$E_f = I \cdot \omega^2$$

$$\Rightarrow \Delta E = I \omega^2 - \frac{m v^2}{2}$$



Q2. a)



$$z = r \omega t$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$\dot{z} = \omega t \cdot r$$

$$\dot{x} = -r \omega \sin \theta$$

$$\dot{y} = r \omega \cos \theta + r \dot{\theta} \sin \theta$$

$$\begin{aligned} \dot{x}^2 &= r^2 \omega^2 \sin^2 \theta - 2 r \dot{\theta} \omega \sin \theta \cos \theta + r^2 \dot{\theta}^2 \sin^2 \theta \\ \dot{y}^2 &= r^2 \omega^2 \cos^2 \theta + 2 r \dot{\theta} \omega \sin \theta \cos \theta + r^2 \dot{\theta}^2 \cos^2 \theta \end{aligned} \quad \left\{ \begin{aligned} \dot{x}^2 + \dot{y}^2 &= r^2 + r^2 \dot{\theta}^2 \end{aligned} \right. \quad (1 + \omega^2 t^2)$$

$$T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2 + \dot{z}^2) = \frac{1}{2} m (r^2 + r^2 \dot{\theta}^2 + r^2 \omega^2 t^2) + \frac{1}{2} m r^2 \omega^2 t^2 + \frac{1}{2} m r^2 \dot{\theta}^2$$

$$U = m g z = m g r \omega t$$



$$b) L = T - U = \frac{m\dot{r}^2}{2} \cdot \csc^2 \alpha + \frac{1}{2} m r^2 \dot{\theta}^2 - mgr \cos \alpha //$$

for r:

$$m\ddot{r} \csc^2 \alpha - m r \dot{\theta}^2 + mg \cos \alpha = 0$$

$$\ddot{r} - r \dot{\theta}^2 \sin^2 \alpha + g \cos \alpha \cdot \sin^2 \alpha = 0 //$$

for θ :

$$m r^2 \ddot{\theta} - 0 = 0 \Rightarrow m r^2 \ddot{\theta} = 0 \Rightarrow \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = 0 \Rightarrow \frac{\partial L}{\partial \dot{\theta}} = m r^2 \dot{\theta} = \text{const}$$

c) Sin, constant θ & constant

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = 0 \Rightarrow \frac{\partial L}{\partial \dot{\theta}} = m r^2 \dot{\theta} = \text{const}$$

$$m r^2 \omega = m r v = L ; \text{ maybe wrong because } \frac{\partial L}{\partial t} = 0$$

$$d) H = \sum p_i \cdot \dot{q}_i - L$$

$$p_r = \frac{\partial L}{\partial \dot{r}} = m \dot{r} \csc^2 \alpha \Rightarrow \dot{r} = \frac{p_r \sin^2 \alpha}{m}$$

$$p_\theta = \frac{\partial L}{\partial \dot{\theta}} = m r^2 \dot{\theta} \Rightarrow \dot{\theta} = \frac{p_\theta}{m r^2}$$

$$H = (p_r \cdot \dot{r} + p_\theta \cdot \dot{\theta}) - \frac{m \dot{r}^2}{2} \csc^2 \alpha - \frac{1}{2} m r^2 \dot{\theta}^2 + mgr \cos \alpha$$

$$H = \frac{p_r^2 \sin^2 \alpha}{m} + \frac{p_\theta^2}{m r^2} - \frac{m p_r^2 \sin^2 \alpha}{m^2 2} - \frac{1}{2} \frac{m r^2 p_\theta^2}{m^2 r^2} + mgr \cos \alpha$$

$$= \frac{p_r^2 \sin^2 \alpha}{2m} + \frac{p_\theta^2}{2m r^2} + mgr \cos \alpha$$

$$E_{\text{me}} = \frac{m \dot{r}^2}{2} \csc^2 \alpha + \frac{1}{2} m r^2 \dot{\theta}^2 + mgr \cos \alpha$$

$$\dot{p}_r = \frac{\partial H}{\partial r} = -\frac{p_\theta^2}{m r^3} - mg \cos \alpha \quad \dot{\theta} = \frac{p_\theta}{m r^2}$$

$$\dot{p}_\theta = -\frac{\partial H}{\partial \theta} = 0 \quad \dot{r} = \frac{\partial H}{\partial p_r} = \frac{p_r \sin^2 \alpha}{m}$$

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e) oscilações rotacionais

$$V = \frac{1}{2} \omega r^2$$

$$\dot{V} = \omega r, \ddot{V} = \omega$$

$$\omega = \frac{L}{mr^2} \Rightarrow \text{rotacional}$$

$$V = \frac{1}{2} \omega r^2$$

$$\dot{V} = \omega r \Rightarrow \alpha = \frac{\ddot{V}}{\dot{V}} = \frac{\omega}{\omega r} = \frac{1}{r}$$

$$\ddot{V} = 0 = K$$

$$p = \frac{1}{2\pi K} \left(\frac{3L^2}{4\pi r^2} \right)$$

$$\omega^2 = \frac{K}{m}$$

$$\ddot{V} = -\frac{L^2}{mr^3} + \omega r \Rightarrow \ddot{V} = -\frac{L^2}{mr^3} + \frac{L}{mr} \Rightarrow \frac{3L}{mr} = K$$

Q3.

a) r_0 e r_1 são os pontos de equilíbrio estável das potências. $\left(\frac{dV}{dr} = 0 \right)$

b) É esperado que a molécula B perca essa energia em seguida, mantendo-se na órbita e voltando para o estado fundamental. [Inicialmente a molécula está oscilando em torno do ponto de equilíbrio. Quando ela muda para o estado eletrônico a tendência é que a molécula perca de oscilar e conserve-se estacionária (amplitude r_1) $r_1 < r_2$]

$$c) \psi(r) = \frac{1}{\sqrt{\pi a_0^3}} e^{-r/a_0} \Rightarrow P = \int |\psi(r)|^2 dr = \int_0^\infty |\psi(r)|^2 dr$$

radial probability distribution is:

$$P(r) = \frac{1}{\pi a_0^3} e^{-2r/a_0} \cdot 4\pi r^2 dr = \frac{4}{a_0^3} r^2 e^{-2r/a_0}$$

$$\frac{dP}{dr} = 0 = 8\pi r e^{-2r/a_0} - \frac{8\pi r^2}{a_0} e^{-2r/a_0} \Rightarrow r = a_0$$

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$$d) \langle r \rangle = \int_0^\infty \psi(r)^* \cdot r \cdot \psi(r) \, dv = \frac{4\pi}{a_0^3} \int_0^\infty r^3 e^{-\frac{2r}{a_0}} dr$$

$v = r^3 \quad dv = 3r^2 dr$
 $dv = 3r^2 dr \quad v = \frac{a_0}{2} e^{-\frac{2r}{a_0}}$

$$I \quad r^3 \cdot \left(-\frac{a_0}{2}\right) e^{-\frac{2r}{a_0}} + \int \left(\frac{3a_0}{2}\right) e^{-\frac{2r}{a_0}} \cdot r^2 dr$$

$v = r^2 \quad dv = 2r dr$
 $dv = 2r dr \quad v = -\frac{a_0}{2} e^{-\frac{2r}{a_0}}$

$$II \quad r^2 \cdot \left(-\frac{a_0}{2}\right) e^{-\frac{2r}{a_0}} + \int \left(\frac{a_0}{2}\right) e^{-\frac{2r}{a_0}} \cdot 2r dr$$

$v = r \quad dv = e^{-\frac{2r}{a_0}}$
 $dv = dr \quad v = -\frac{a_0}{2} e^{-\frac{2r}{a_0}}$

$$III \quad r \cdot \left(-\frac{a_0}{2}\right) e^{-\frac{2r}{a_0}} + \int \left(\frac{a_0}{2}\right) e^{-\frac{2r}{a_0}} \cdot dr$$

$= r \left(\frac{a_0}{2}\right) e^{-\frac{2r}{a_0}} - \frac{a_0^2}{2} e^{-\frac{2r}{a_0}}$

$$\langle r \rangle = \frac{4}{a_0^3} \left[-\frac{r^3 a_0}{2} e^{-\frac{2r}{a_0}} + \frac{3a_0}{2} \left[-\frac{a_0 r^2}{2} e^{-\frac{2r}{a_0}} + a_0 \left(-\frac{a_0 r}{2} e^{-\frac{2r}{a_0}} - \left(\frac{a_0}{2}\right)^2 e^{-\frac{2r}{a_0}} \right) \right] \right]_0^\infty$$

$$= \frac{4e^{-\frac{2r}{a_0}}}{a_0^3} \left[-\frac{r^3 a_0}{2} - \frac{3a_0^2 r^2}{4} - \frac{3a_0^3 r}{4} - \frac{3a_0^4}{8} \right]_0^\infty$$

$$\langle r \rangle = \frac{3a_0}{2}$$

04. a) 100(0.69)

Antes colisión.

Después colisión.



B. $p = 0; E_s = m_0 c^2$ ✓

C. $E = E_A + E_B = \frac{8}{3} m c^2$ ✓

$p = \frac{4}{3} m c$

A. $p = \gamma m v$ $\gamma = \frac{5}{3}$

$= m \cdot \frac{4}{3} c \cdot \frac{1}{\sqrt{1 - \frac{16}{25}}} = \frac{4}{3} m c \cdot \frac{5}{3} = \frac{20}{9} m c$ $E_A = \frac{5}{3} m c^2$ ✓

0.6 $\beta = 0.56$ $\frac{1}{\gamma} = \frac{3}{5}$

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$$b) \frac{5c}{2} = \frac{pc}{\epsilon_0} \Rightarrow v_c = \frac{\frac{4}{3}mc^3}{\frac{4}{3}mc^2} = \frac{c}{2}$$

$$p_c = \gamma m v_c = \frac{4}{3} m c$$

$$E_c = \gamma m c^2 = \frac{4}{3} m c^2$$

$$\gamma_1 = \frac{1}{\sqrt{1 - \frac{1}{4}}} = \frac{2}{\sqrt{3}}$$

$$c) \frac{4}{3} m c = \gamma m v_c \Rightarrow \frac{4}{3} m c = \frac{2}{\sqrt{3}} \frac{M c}{2} \Rightarrow M = \frac{4\sqrt{3}}{3} m \Rightarrow m = \frac{4m}{\sqrt{3}}$$

QS.

$$a) dU = dQ - dW \quad p = \frac{nRT}{V}$$

$$ncdT = TdS - pdv$$

$$ds = \frac{ncdT}{T} - \frac{nRdv}{v} \Rightarrow \Delta S = nc \ln\left(\frac{T_1}{T_2}\right) - nR \ln\left(\frac{v_1}{v_2}\right)$$

b) A → B

$$dU = dQ - dW \Rightarrow W = \Delta Q$$

$$\Delta U = 0$$

$$p_A v_A = p_B v_B = 0$$

$$p_A v_A = p_B v_B$$

$$\frac{nRT}{V}$$

$$Q = nc\Delta T + p\Delta v$$

$$Q = n\Delta T(c + R)$$

$$Q = n\Delta T \cdot c_p$$

$$W_1 = \int_{v_1}^{v_2} p dv = nRT_1 \ln\left(\frac{v_2}{v_1}\right) = -Q_1$$

C → D

$$W_3 = nRT_1 \ln\left(\frac{v_4}{v_3}\right) = -Q_3$$

D → A

$$Q_4 = W_4 = nc\Delta T_2$$

$$B \rightarrow C \quad \Delta U = -W$$

$$Q_2 = 0 \quad W_2 = nc\Delta T_1$$

$$\Delta T = T_1 - T_2 = \Delta T_2$$

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c) $\eta = \frac{w_1}{Q_1} = \frac{Q_1 - Q_2}{Q_1} = 1 - \frac{Q_2}{Q_1} = 1 - \frac{T_f}{T_g}$

1/2 de uma fórmula
para fator que é usado no trabalho.

$\Delta U = 0 \Rightarrow w = \Delta Q = Q_1 - Q_2$

$\frac{Q_1}{Q_2} = \frac{T_g}{T_f}$

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a)



$r < R$

$Q_{enc} = \frac{Q}{2\pi R l} \cdot 2\pi r l$

$E = \frac{Q_{enc}}{2\pi r l \epsilon_0} = \frac{r p}{2\epsilon_0}$

$r > R$
 $E = \frac{Q}{2\pi r l \epsilon_0} = \frac{R p}{2\epsilon_0}$
 $Q_{enc} = \pi R^2 l p$

$Q_{enc} = \pi r^2 l p$

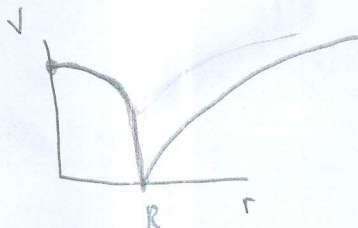
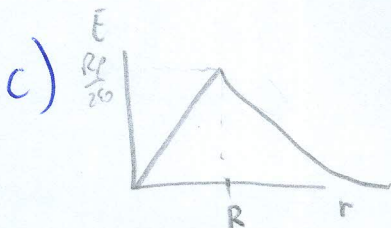
b)

$r < R$

$V = \int_R^r -E dr = \int_R^r -\frac{r p}{2\epsilon_0} dr = -\frac{p}{2\epsilon_0} \left(\frac{r^2 - R^2}{2} \right)$

$r > R$

$V = \int_R^r -\frac{R^2 p}{2\epsilon_0 r} dr = \frac{R^2 p}{2\epsilon_0} \left[\ln\left(\frac{r}{R}\right) \right]$



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d) Porque a velocidade da luz é constante em todos os referenciais inerciais (constante da velocidade da luz)

$$E = \frac{Q_{enc}}{4\pi\epsilon_0 r^2}$$

07.

a) $\vec{E} = E_0 \cdot e^{i(\vec{k}\vec{r} - \omega t)}$

$$\nabla \vec{E} = i\vec{k} \vec{E}$$

$$\frac{\partial \vec{E}}{\partial t} = -i\omega \vec{E}$$

$$\begin{aligned} H &= E_0 \cdot e^{i(\vec{k}\vec{r} - \omega t)} \\ E &= E_0 \cdot e^{i(\vec{k}\vec{r} - \omega t)} \end{aligned}$$

$$\frac{\omega}{k} = \frac{c}{n}$$

$$\begin{cases} i\vec{k} \times \vec{E} - i\omega \vec{B} = 0 \\ i\vec{k} \cdot \vec{B} = 0 \\ i\vec{k} \cdot \vec{E} = 0 \\ i\vec{k} \times \vec{H} + i\omega \vec{D} = \vec{J} \end{cases}$$

b) $\rho = n$
 $i\vec{k} \times \vec{H} + \frac{i}{n} \omega \vec{H} = \vec{J}$

$$\frac{c}{v} = n \quad \rho = \frac{q}{v}$$

$$\begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ i\vec{k} & \vec{H} & \vec{J} \end{vmatrix} = i\vec{k} \vec{H} \hat{z} - i\vec{k} \vec{H} \hat{x}$$

$$i\vec{k} \times \vec{H} + i\omega \vec{E} = \vec{J}$$

$$i\vec{k} \vec{H} \hat{z} - i\vec{k} \vec{H} \hat{x} + \frac{i}{n} \omega \vec{H} = \vec{J}$$

$$\vec{J} = \frac{i}{n} \omega \vec{H}$$

c)

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Q8.

$$a) \frac{\partial P}{\partial t} = -\frac{\partial \mathcal{H}}{\partial x} \quad \frac{\partial P}{\partial t} = \frac{\partial [\psi^*(x,t) \cdot \psi(x,t)]}{\partial t} = \frac{\partial \psi^*(x,t)}{\partial t} \cdot \psi(x,t) + \psi^*(x,t) \cdot \frac{\partial \psi(x,t)}{\partial t}$$

$$= -\frac{\partial \mathcal{H}}{\partial x}$$

$$i\hbar \cdot \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + V(x) \psi(x,t)$$

$$i\hbar \left(\frac{\partial P}{\partial t} \cdot \frac{1}{\psi^*(x,t)} - \frac{\partial \psi^*(x,t)}{\partial t} \cdot \frac{\psi(x,t)}{\psi^*(x,t)} \right) = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + V(x) \psi(x,t)$$

Using

$$-i\hbar \frac{\partial \psi^*}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi^*}{\partial x^2} + V(x) \psi^* \rightarrow \frac{\partial \psi^*}{\partial t} = -\frac{i\hbar}{2m} \frac{\partial^2 \psi^*}{\partial x^2} + \frac{iV(x) \psi^*}{\hbar}$$

$$i\hbar \left(\frac{\partial P}{\partial t} \cdot \frac{1}{\psi^*} + \left(\frac{i\hbar}{2m} \frac{\partial^2 \psi^*}{\partial x^2} - \frac{iV(x) \psi^*}{\hbar} \right) \cdot \frac{\psi}{\psi^*} \right) = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + V(x) \psi$$

$$i\hbar \frac{\partial P}{\partial t} \cdot \frac{1}{\psi^*} = \frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + \cancel{V(x) \psi(x)} + \frac{\hbar^2}{2m} \frac{\partial^2 \psi^*}{\partial x^2} \cdot \frac{\psi}{\psi^*} - \cancel{V(x) \psi}$$

$$\frac{\partial P}{\partial t} = \frac{i\hbar}{2m} \frac{\partial^2 \psi}{\partial x^2} \cdot \psi^* + \frac{iV(x) \psi(x)}{\hbar} - \frac{i\hbar}{2m} \frac{\partial^2 \psi^*}{\partial x^2} \cdot \psi + V(x) \psi(x)$$

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$$\frac{\partial p}{\partial t} = \frac{i\hbar}{2m} \left[\frac{\partial^2 \psi}{\partial x^2} \psi^* - \frac{\partial^2 \psi^*}{\partial x^2} \psi \right] = \frac{\partial \psi^*}{\partial x} \frac{\partial \psi}{\partial x} + \psi^* \frac{\partial^2 \psi}{\partial x^2} - \frac{\partial^2 \psi^*}{\partial x^2} \psi - \frac{\partial \psi^*}{\partial x} \frac{\partial \psi}{\partial x}$$

$$b) \frac{\partial y}{\partial x} = \frac{i\hbar}{2m} \left[\frac{\partial^2 \psi}{\partial x^2} \psi^* - \frac{\partial^2 \psi^*}{\partial x^2} \psi \right]$$

$$\frac{\partial y}{\partial x} = \frac{i\hbar}{2m} \frac{\partial}{\partial x} \left[\psi^* \frac{\partial \psi}{\partial x} - \frac{\partial \psi^*}{\partial x} \psi \right]$$

$$y = -\frac{i\hbar}{2m} \left[\psi^* \frac{\partial \psi}{\partial x} - \frac{\partial \psi^*}{\partial x} \psi \right]$$

$$c) \langle x \rangle = \int \psi^* x \psi dx \quad \langle p \rangle = \int \psi^* (-i\hbar) \frac{\partial \psi}{\partial x} dx$$

$$\frac{d\langle x \rangle}{dt} = \int \frac{\partial (\psi^* x \psi)}{\partial t} dx = \int \left(\frac{\partial \psi^*}{\partial t} x \psi + \psi^* \frac{\partial x \psi}{\partial t} \right) dx$$

$$= \int \left(\left[-\frac{i\hbar}{2m} \frac{\partial^2 \psi^*}{\partial x^2} + \frac{i}{\hbar} \psi^* \right] x \psi + \psi^* x \left[\frac{i\hbar}{2m} \frac{\partial^2 \psi}{\partial x^2} + \frac{i}{\hbar} \psi \right] \right) dx$$

$$= \int \left(-\frac{i\hbar}{2m} \frac{\partial^2 \psi^*}{\partial x^2} x \psi + \frac{i\hbar}{2m} \psi^* x \frac{\partial^2 \psi}{\partial x^2} \right) dx = -\frac{i\hbar}{2m} \int \left(x \psi \frac{\partial^2 \psi^*}{\partial x^2} - x \psi^* \frac{\partial^2 \psi}{\partial x^2} \right) dx$$

(9)

$$\frac{d\langle x \rangle}{dt} = \frac{i\hbar}{2m} \int x \left[\psi^* \frac{\partial^2 \psi}{\partial x^2} + \psi \frac{\partial^2 \psi^*}{\partial x^2} \right] dx \quad \langle p \rangle = \int \psi^* (-i\hbar) \frac{\partial \psi}{\partial x} dx$$

$$= \frac{i\hbar}{2m} \int x \cdot \frac{\partial}{\partial x} \left[\psi^* \frac{\partial \psi}{\partial x} - \psi \frac{\partial \psi^*}{\partial x} \right] dx$$

$$v = x \quad dv = \frac{\partial}{\partial x} \left(\psi^* \frac{\partial \psi}{\partial x} - \psi \frac{\partial \psi^*}{\partial x} \right)$$

$$dv = dx$$

$$= \frac{i\hbar}{2m} \left[\underbrace{\left(\psi^* \frac{\partial \psi}{\partial x} - \psi \frac{\partial \psi^*}{\partial x} \right)}_{\substack{\text{falls } \psi \rightarrow 0 \text{ bei } \pm\infty \\ \text{mit } \frac{1}{x} \cdot x = 1}} \cdot x \right]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \psi^* \frac{\partial \psi}{\partial x} - \psi \frac{\partial \psi^*}{\partial x} dx$$

$$\Rightarrow \frac{i\hbar}{2m} \int_{-\infty}^{\infty} \left(\psi^* \frac{\partial \psi}{\partial x} - \psi \frac{\partial \psi^*}{\partial x} \right) dx$$

$$= \frac{i\hbar}{2m} \left(\langle p \rangle + \int_{-\infty}^{\infty} \psi^* \frac{\partial \psi}{\partial x} dx \right) = \frac{i\hbar}{2m} \langle p \rangle + \langle p \rangle = \boxed{\frac{\langle p \rangle}{m}}$$

$$v = x \quad dv = \frac{\partial \psi}{\partial x} \quad \int_{-\infty}^{\infty} \psi^* \frac{\partial \psi}{\partial x} dx = \langle p \rangle$$

Q9

$$c) \hat{N} \hat{a} |n\rangle = \hat{a}^\dagger \hat{a} \hat{a} |n\rangle = [\hat{a}^\dagger \hat{a} + \hat{a} \hat{a}^\dagger - \hat{a} \hat{a}^\dagger] \hat{a} |n\rangle$$

$$= [\hat{a}^\dagger \hat{a} + \hat{a} \hat{a}^\dagger] \hat{a} |n\rangle = -\hat{a} |n\rangle + \hat{a} n |n\rangle = (n-1) \hat{a} |n\rangle$$

$$\hat{N} \hat{a}^\dagger |n\rangle = \hat{a}^\dagger \hat{a} \hat{a}^\dagger |n\rangle = \hat{a}^\dagger [\hat{a} \hat{a}^\dagger + \hat{a}^\dagger \hat{a} - \hat{a}^\dagger \hat{a}] |n\rangle \quad \text{aufzuschub!}$$

$$= \hat{a}^\dagger [1 + \hat{a} \hat{a}^\dagger] |n\rangle = (n+1) \hat{a}^\dagger |n\rangle \quad \text{aufzuschub! } n+1 = n'$$

EVF 2011-250

02/04/2016

b) $\langle n | n \rangle = 1$ $\frac{a \rightarrow a^\dagger}{|a\rangle = c_n |n\rangle}$

$n = \langle n | n \rangle = \langle n | a^\dagger a | n \rangle = \langle a n | a n \rangle$

$\sqrt{n} \cdot \sqrt{n} = n$

$n^2 = n(n+1)$
 $n = n+1$

$\langle n | n \rangle = n!$

$\langle n | a^\dagger a | n \rangle = c_n \langle n | a^\dagger | n-1 \rangle$

$c_n \langle n-1 | a | n \rangle^* = |c_n|^2$

$c_n \langle n-1 | n-1 \rangle = |c_n|^2 \langle n-1 | n-1 \rangle = 1$

$\hat{a} | n \rangle = \sqrt{n} | n-1 \rangle$

$n > 0$

$n = 0$

$0 \rightarrow$

$\hat{a} | 0 \rangle = 0$

$n \rightarrow \infty$

$|c_n|^2 = n$

$|c_n| = \sqrt{n}$

c) $\hat{N} \hat{a} | n \rangle = \hat{a}^\dagger \hat{a} \hat{a} | n \rangle = (\hat{a}^\dagger \hat{a} + \hat{a} \hat{a}^\dagger - \hat{a} \hat{a}^\dagger) \hat{a} | n \rangle = (\{\hat{a}^\dagger, \hat{a}\} - \hat{a} \hat{a}^\dagger) \hat{a} | n \rangle$

$(1 - \hat{a} \hat{a}^\dagger) \hat{a} | n \rangle = -\hat{a} | n \rangle - \hat{a} | n-1 \rangle = (-n+1) \hat{a} | n \rangle$

$\hat{N} \hat{a} | n \rangle = \hat{a}^\dagger \hat{a} \hat{a} | n \rangle = \hat{a}^\dagger (\hat{a} \hat{a}^\dagger + \hat{a}^\dagger \hat{a} - \hat{a}^\dagger \hat{a}) | n \rangle$ $n' = -n+1$

$= \hat{a}^\dagger (\{\hat{a}, \hat{a}^\dagger\} - \hat{a}^\dagger \hat{a}) | n \rangle = \hat{a}^\dagger (1 - \hat{a}^\dagger \hat{a}) | n \rangle = \hat{a}^\dagger (1 - n) | n \rangle = (1-n) \hat{a} | n \rangle$

$\hat{a} | n \rangle = c_n | n-1 \rangle$

$n' = 1-n$

$n = \langle n | n \rangle = \langle n | \hat{a}^\dagger \hat{a} | n \rangle = c_n \langle n | \hat{a}^\dagger | n-1 \rangle$

$= c_n \langle n-1 | \hat{a} | n \rangle^* = |c_n|^2 \langle n-1 | n-1 \rangle$

$\hat{a} | n \rangle = \sqrt{n} | n-1 \rangle$

$c_n = \sqrt{n}$

all out of the net

$\sqrt{n} > 0 \Rightarrow n \leq 1$

$n=0 \Rightarrow c_n=1$

$\sqrt{n} > 0 \Rightarrow n > 0$

all

Q12

a) $\mu(T) = \alpha T^4$

$U = \mu(T) \cdot V$ e $S = s(T) \cdot V$, $P = \frac{\mu(T)}{3}$

$du = d\epsilon - dw$

$du = Tds - pdv$

$\frac{du}{dv} = T \left(\frac{ds}{dv} \right)_T - P$

$\mu(T) = T \left(\frac{\partial \mu}{\partial T} \right)_V - P$

$\mu(T) = \frac{T}{3} \left(\frac{\partial \mu}{\partial T} \right)_V - \frac{\mu(T)}{3}$

$\left(\frac{\partial s}{\partial v} \right)_T = \left(\frac{\partial p}{\partial T} \right)_V$

$3\mu(T) + \mu(T) = \frac{T}{3} \frac{\partial \mu}{\partial T}$

$\frac{dT}{T} = \frac{d\mu}{4\mu(T)}$

$\mu(T) = AT^4$

$S = k_B \int_0^\infty \frac{\omega^3}{e^{\beta \hbar \omega} - 1} d\omega$

nº de fotões por modo e energia de cada modo

$U = k_B \int_0^\infty \frac{\omega^3}{e^{\beta \hbar \omega} - 1} d\omega = \frac{k_B}{(\beta \hbar)^4} \int_0^\infty \frac{x^3}{e^x - 1} dx = \frac{15}{16} \frac{k_B^4}{15 \hbar^3} T^4 = \frac{15}{16} \frac{k_B^4}{15 \hbar^3} T^4$

b) $\bar{z} = \sum_n e^{-\beta \epsilon_n} = \frac{1}{1 - e^{-\beta \epsilon_1}} \Rightarrow \ln \bar{z} = -\ln(1 - e^{-\beta \epsilon_1})$

$\bar{u} = \frac{1}{\beta} \left[\frac{1}{1 - e^{-\beta \epsilon_1}} \cdot (-e^{-\beta \epsilon_1}) \cdot (-\epsilon_1) \right] = \frac{1}{\beta} \frac{e^{-\beta \epsilon_1}}{1 - e^{-\beta \epsilon_1}} = \frac{1}{\beta} \frac{1}{e^{\beta \epsilon_1} - 1}$

$\bar{u} = \frac{1}{\beta} \frac{1}{e^{\beta \epsilon_1} - 1} = \frac{1}{\beta} \frac{1}{e^{\beta \hbar \omega} - 1}$

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